

## EXAMINATION 1

**Directions.** Do both problems (weights are indicated). This is a closed-book closed-note exam except for one  $8\frac{1}{2} \times 11$  inch sheet containing any information you wish on both sides. You are free to approach the proctor to ask questions – but he will not give hints and will be obliged to write your question and its answer on the board. Roots, circular functions, *etc.*, may be left unevaluated if you do not know them. Use a bluebook. Do not use scratch paper – otherwise you risk losing part credit. Cross out rather than erase any work that you wish the grader to ignore. Justify what you do. Box or circle your answer.

**1. (50 points)**

A book has its front cover facing up (the normal to the cover is along  $\hat{z}$ ). Its sentences are parallel to the  $\hat{x}$  direction, and its binding is parallel to the  $\hat{y}$  direction. Consider the “body”  $(x, y, z)$  axes to be attached to the book, with their origin at its CM. Define the “space”  $(x', y', z')$  axes initially to be the same as the  $(x, y, z)$  axes; however, the  $(x', y', z')$  axes are fixed – they don’t change when the book rotates.

**(a) (10 points)**

Suppose the book is rotated about its  $z$  axis by  $45^\circ$  counterclockwise (carrying the body axes with it). The space axes remain fixed. Write down the transformation matrix  $\Lambda_a^t$  such that

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \Lambda_a^t \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} .$$

**(b) (10 points)**

Instead suppose the book is rotated about its  $x$  axis by  $45^\circ$  counterclockwise (carrying the body axes with it). The space axes remain fixed. Write down the transformation matrix  $\Lambda_b^t$  such that

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \Lambda_b^t \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} .$$

**(c) (15 points)**

Instead suppose the book is first rotated as in **(a)**, next rotated as in **(b)**. Write down the transformation matrix  $\Lambda_c^t$  such that

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \Lambda_c^t \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} .$$

**(d) (15 points)**

Write down the inverse of  $\Lambda_c^t$ .

**2. (50 points)**

With respect to a fixed set of Cartesian coordinates  $(x, y, z)$ , the position  $\mathbf{r}(t)$  of a particle of mass  $m$  is given by

$$\mathbf{r}(t) = \hat{\mathbf{x}}x_0 + \hat{\mathbf{y}}v_0t ,$$

where  $x_0$  and  $v_0$  are constants.

**(a) (10 points)**

With respect to the origin, write down the particle’s moment of inertia  $I(t)$ .

**(b) (15 points)**

With respect to the origin, write down the magnitude and direction of the particle’s *angular* velocity  $\vec{\omega}(t)$ .

**(c) (10 points)**

For the conditions specified in this problem, the product of  $I(t)$  and  $\vec{\omega}(t)$  is  $\mathbf{L}$ , the particle’s angular momentum with respect to the origin. Write down  $\mathbf{L}$ . Is it a function of time  $t$ ? If so, a torque must be acting on the particle – what is the source of this torque? Explain.

**(d) (15 points)**

Imagine that the particle in **(a)**–**(c)** is an element of fluid. The fluid’s velocity field  $\mathbf{v}(\mathbf{r})$  is given by

$$\mathbf{v}(\mathbf{r}) = \hat{\mathbf{y}}v_0 \frac{x}{x_0} ,$$

where, as above,  $x_0$  and  $v_0$  are constants. Can  $\mathbf{v}(\mathbf{r})$  be expressed as the gradient of a scalar field  $u(\mathbf{r})$ , *i.e.*

$$\mathbf{v}(\mathbf{r}) = -\nabla u(\mathbf{r}) ?$$

If so, what is  $u(\mathbf{r})$ ? If not, why not?